# Towards Internet of Things (IoT)supported Mobile Augmented Reality



Maria Gorlatova November 10, 2021





# About the Speaker

- Nortel Networks Assistant Professor, ECE/CS, Duke University
- Previously:
  - Associate Research Scholar, Princeton University, Electrical Engineering
  - > Ph.D. Columbia University, Electrical Engineering
  - Industry positions:



Dukeuniversity











## Duke University Intelligent Interactive Internet of Things (I<sup>3</sup>T) Lab

• Core research direction: reliable context-aware mobile AR





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#### **IoT-supported Mobile AR**



## Mobile AR: Current State and Limitations

# Already: impressive capabilities in merging physical and digital worlds



Limitations:

- Resource consumption
- Errors in semantic and spatial awareness

AR-assisted surgery AR in an art gallery

Demo video: Cognitive context-adaptive AR in an art gallery: https://sites.duke.edu/timscargill/ar-art-gallery/

#### Failures in Semantic & Spatial Awareness

- Semantic errors: incorrect holograms rendered
- **Spatial errors**: holograms rendered in the wrong place



Incorrect scale

Unintended motion (drift)

#### Major improvements are required to make mobile AR reliable

T. Scargill, J. Chen, M. Gorlatova, Here to Stay: Measuring Hologram Stability in Markerless Smartphone Augmented Reality. arXiv: 2109.14757, Sept. 2021.

#### Edge Computing-supported Mobile AR



 Edge computing: providing computing services close to mobile AR devices



#### Edge Computing-supported Mobile AR





Edge computing for depth Edge computing for gaze-based cognitive data inpainting context detection

X. Ran, C. Slocum, Y.-Z. Tsai, K. Apicharttrisorn, M. Gorlatova, J. Chen, Multi-User Augmented Reality with Communication Efficient and Spatially Consistent Virtual Objects, in *Proc. ACM CoNEXT'20*, Dec. 2020.

G. Lan, B. Heit, T. Scargill, M. Gorlatova, GazeGraph: Graph-based Few-Shot Cognitive Context Sensing from Human Visual Behavior, in *Proc. ACM SenSys'20*, Nov. 2020.

#### IoT-supported Mobile AR

- Edge computing for interfacing with IoT devices
- IoT sensors and actuators supporting mobile AR in developing environmental awareness
  - Persistent environmental monitoring
  - Environmental control
    Smart cameras
     Mobile AR devices



#### Integrated AR+Edge+IoT Platforms

• Mobile AR ↔ Edge ↔ IoT connectivity can be readily established



Different IoT sensors and actuators integrated with mobile AR platforms



#### Challenges include:

- Low-end IoT devices' spatial awareness
- Learning the extent of environment controllability

# New Algorithms: Exploiting Multiple Views of the Same Scene

- DNN-based image recognition enables seamless contextual AR
- Challenge: DNNs make mistakes
  - > Distortions, occlusions, non-standard object poses
- Multiple views of a scene can help







#### CollabAR: Collaborative Image Recognition for Mobile AR



- Improves recognition accuracy by 16% to 20% in severe distortions scenario
- Many other opportunities to exploit IoT cameras for semantic awareness

#### Auxiliary-assisted Multiview Ensemble Learning

- G. Lan, Z. Liu, Y. Zhang, T. Scargill, J. Stojkovic, C. Joe-Wong, M. Gorlatova, Edge-assisted Collaborative Image Recognition for Mobile Augmented Reality, to appear in the ACM Transactions on Sensor Networks, Vol. 18, No 1, Feb. 2022.
- Z. Liu, G. Lan, J. Stojkovic, Y. Zhang, C. Joe-Wong, M. Gorlatova, CollabAR: Edge-assisted Collaborative Image Recognition for Mobile Augmented Reality, in Proc. *IEEE/ACM IPSN'20*, April 2020. IEEE/ACM IPSN Best Research Artifact Award.

#### New Algorithms: Scene Characterization for Spatial Awareness in Mobile AR

 Challenge: automatically detecting and *quantifying* conditions that cause spatial artifacts



Featureless (left) and dark (right) scenes are associated with spatial artifacts



Featureless areas have low entropy

□ T. Scargill, S. Hurli, J. Chen, M. Gorlatova, Demo: Will it Move? Indoor Scene Characterization for Hologram Stability in Mobile AR, in *Proc. ACM HotMobile* 21, Feb. 2021.

# Summary

- Modern mobile AR has limitations in environmental awareness
  - Semantic, spatial awareness
- IoT sensors and actuators can help



• Developing platforms and algorithms to enable this vision



## Acknowledgements





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## Questions?

• E-mail the speaker: maria.gorlatova@duke.edu

